

## Oscillations in Differential Equations With State-Dependent Delays

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Recently, O.Arino, M.L.Hbid and R.Bravo de la Parra proposed a model in [1] describing the evolution of a population of fish whose larvae share a limited resource. The model is made of two equations: a state equation governing the evolution of the total number, which is a delay differential equation with variable delay, and an ordinary differential equation satisfied by the delay with coefficients expressed in terms of the state variable. A simplified version of the model which was presented is the following delay differential equations with delay depending directly on the state.

$$\begin{cases} \frac{dx}{dt} = -f(x(t - \tau(t))), \\ \frac{d\tau}{dt} = h(x(t), \tau(t)). \end{cases}$$

In [2], the authors studied the existence of slow oscillations and periodic slow oscillating solutions.

Here, we consider a general abstract formulation of this system :

$$\begin{cases} \frac{dx}{dt} = -f(x(t - \tau(x_t))), \\ \int_{t-\tau(x_t)}^t k(x(s))ds = k_o \end{cases}$$

and we extend, for this class of differential equations, results about necessary and sufficient conditions of oscillations which are well known in

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the case when the delay is constant, and in some classes of time-depending delay differential equations

## References

- [1] O.Arino,M.L.Hbid and R.Bravo de la Parra,A Mathematical model of population of fish in the larval stage: density-dependence effects.Math.Biosci.150,1998,1-20
- [2] O.Arino,K.P.Hadeler and M.L.Hbid, Existence of periodic solutions for delay differential equations with state dependent delay.J.Diff.Equat.144,N2,1998,263-301