

## Feedback Control for Competition Models with Inhibition in the Chemostat

Gonzalo Robledo<sup>1</sup> and Jean Luc Gouzé<sup>2</sup> .

We consider the feedback control problem for a model of competition among two microorganisms with one limiting resource in the chemostat with nonmonotone uptake functions described by the system of differential equations:

$$\begin{cases} s' = D(s_{in} - s) - \frac{x_1}{y_1} f_1(s) - \frac{x_2}{y_2} f_2(s) \\ x_1' = x_1(f_1(s) - D) \\ x_2' = x_2(f_2(s) - D) \end{cases} \quad (1)$$

In model (1),  $s(t)$  denotes the concentration of limiting resource and  $x_i$  denotes the density of the  $i$ th population of microorganisms at time  $t$ ,  $f_i(s)$  is a nonmonotone and unimodal function (*e.g.* a Haldane type function) and represents the case when the limiting resource is essential at low concentrations but may be inhibiting or toxic at higher concentrations for the growth of the  $i$ th population,  $y_i$  is a growth yield constant;  $D$  and  $s_{in}$  denote, respectively, the dilution rate of the chemostat and the concentration of the growth limiting resource.

Competition theory for the chemostat models (see [1] and [4]) predicts that coexistence of species for model (1) is not possible; Control theory allows to obtain coexistence considering limiting resource and density of microorganisms as state variables and dilution rate  $D$  or (and) input nutrient  $s_{in}$  as control variable(s).

In [2], De Leenheer and Smith study the feedback control of model (1) with monotone functions  $f_i$ . In the present work we consider  $D$  as the

feedback control variable and we suppose that the only output available is the total biomass  $x_1 + x_2$ , *i.e.* we suppose  $D = \alpha g(x_1 + x_2)$  with  $\alpha > 0$  and  $g$  a continuous and positive real function. We obtain sufficient conditions for the coexistence of microorganisms (obtained as a globally asymptotically stable critical point); Asymptotically autonomous dynamical systems theory and Monotone dynamical systems theory are the main tools employed. Remarks about the robustness of model are shown, if the functions  $f_i$  are only known by the lower and upper envelope.

## References

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<sup>1</sup>INRIA Sophia Antipolis, Projet COMORE, BP 93 – 06902 Sophia Antipolis Cedex France (e-mail: grobledo@sophia.inria.fr).

<sup>2</sup>INRIA Sophia Antipolis, Projet COMORE, BP 93 – 06902 Sophia Antipolis Cedex France (e-mail: gouze@sophia.inria.fr).